

# TIME SERIES FORECASTING

FORECASTING  $\rightarrow$  Prediction

Given a time series

$$x_i, x_{i-1}, \dots$$

We want to estimate the future values in the series, i.e. we want

$$\hat{x}_{i+D} = f(x_i, x_{i-1}, \dots, x_{i-W+1})$$

$$D \geq 1$$

historical values used to estimate new value.

$W :=$  Window size

There is a connection between TIME SERIES FORECASTING and REGRESSION.

REGRESSION uses pairs of measurements  $(x_1, y_1), \dots, (x_N, y_N)$  to build a model  $f()$  such that

$$\text{RESPONSE } \leftarrow \hat{y}_i = f(x_i)$$

There are four options, since  $X$  and  $Y$  can both be either SCALARS or VECTORS

$X \rightarrow$  SCALAR, SIMPLE REGRESSION

$X \rightarrow$  VECTOR, MULTIPLE REGRESSION

$Y \rightarrow$  SCALAR, UNIVARIATE REGRESSION

$Y \rightarrow$  VECTOR, MULTIVARIATE REGRESSION

OSS: Classification can be formalized as a

If we have multiple classes for each row of our dataset then we can have MULTIPLE - MULTIVARIATE REGRESSION.

Time series forecasting problem can be formalized as a MULTIPLE - UNIVARIATE regression problem.

Regression problem can be thought of as "curve fitting" problem, since we want to find the curve that intersects our points.



If we see the  $x$ -axis as time, then we can think about REGRESSION as a method that let's us extrapolate info. from the past.

$x = \text{time index.}$

Consider a random process

$$X_1, \dots, X_i, X_{i+1}, \dots$$

if we fix the time at  $i$   
we have a set of r.v.  $\{X_{i-1}, \dots, X_1\}$

!

Model to do TIME SERIES FORECASTING

$$\hat{X}_{i+h} = f(X_i, X_{i-1}, \dots)$$

A good estimator is one that maximizes the expected value

$$E[\hat{X}_{i+h} | X_i, X_{i-1}, \dots]$$

If we work with observations, then we can define the POINT-WISE ERROR as

$$e_i := \hat{X}_i - X_i$$

By computing the point-wise error at different points during our forecasting then we can define,

- MEAN SQUARED ERROR,

$$MSE = \frac{1}{N} \cdot \sum_{j=1}^N e_j^2$$

MOST  
COMMONLY  
USED!

- MEAN ABSOLUTE DIFFERENCE

$$MAD = \frac{1}{N} \sum_{j=1}^N |e_j|$$

## COMMON PREDICTION METHODS

$$\hat{x}_{i+h} = f(x_i, x_{i-1}, \dots)$$

- NAIVE - 1

$$\hat{x}_{i+h} := x_i$$

Good if there is  
no trend, or if  
D is small.

## - NAIVE-2

$$\hat{x}_{i+D} := x_i \left( 1 + \frac{x_i - x_{i-1}}{x_{i-1}} \right)$$

Not good  
if there is  
noise

## - MOVING AVERAGE

$$\hat{x}_{i+D} := \frac{1}{W} \sum_{j=i-W+1}^i x_j$$

Good for smoothing the noise, but  
it does not take into account the  
trend.

All  $W$  previous points have all  
the same importance in the basic  
version of MOVING AVERAGE.

# - WEIGHTED MOVING AVERAGE

$$\hat{x}_{i+D} := \frac{1}{W} \sum_{j=i-W+1}^i x_j \cdot w_j$$

A weight  $w_j$  is introduced to scale the importance of each observation.

Generally,

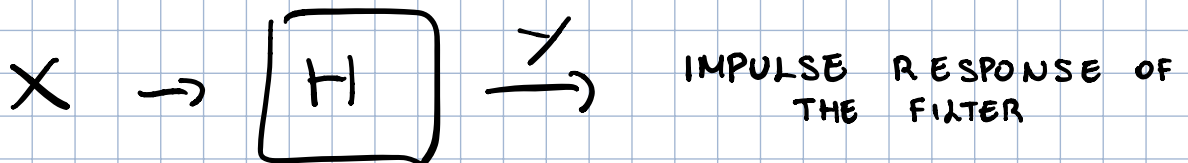
Further back in  $\rightarrow$  less importance  
time

OSS : Consider the following LINEAR TIME-INVARIANT  
? FILTER, which is a linear convolution

(LPF)

$$y(i) = \sum_{k=0}^N \underbrace{h(k)} \cdot (i-k)$$

LINEAR  
PREDICTION  
FILTER



We can map WMA as one of such filters.

# SINGLE EXPONENTIAL SMOOTHING

In this case we have,

$$\hat{X}_{i+d} = \alpha \cdot X_i + \alpha(1-\alpha)X_{i-1} + \alpha(1-\alpha)^2 X_{i-2} + \dots$$

$$\hat{X}_{i+d} = \alpha X_i + (1-\alpha) \cdot \hat{X}_i$$

where  $\alpha \in (0, 1)$  is a SMOOTHING PARAMETER.

Not that good for time series with a very steep trend.

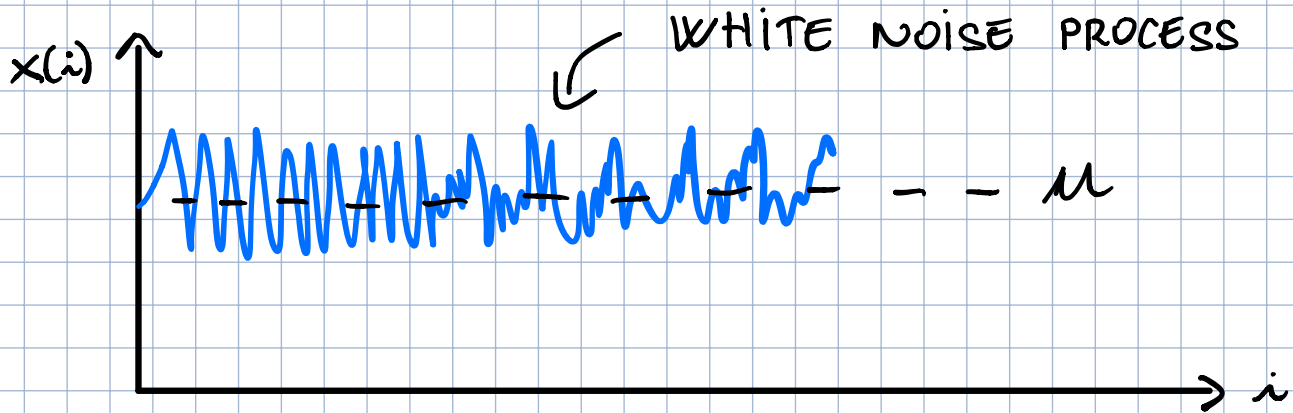
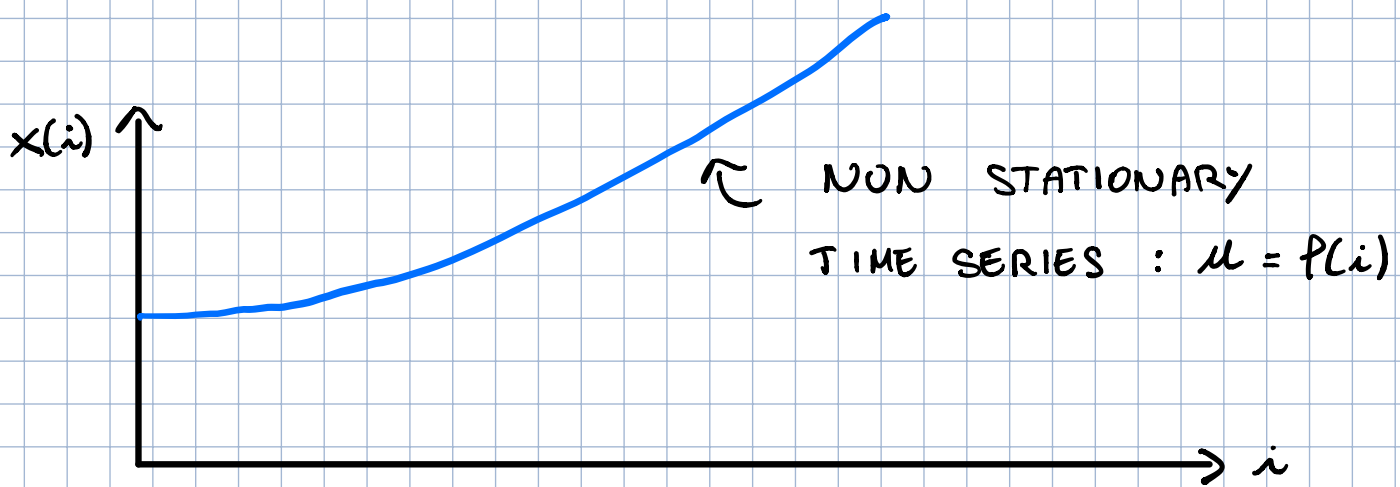
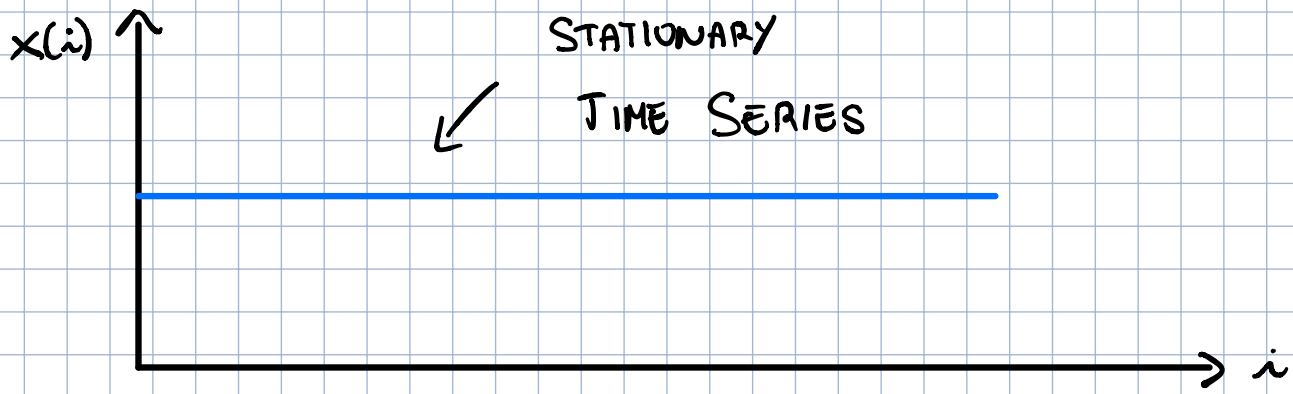
Q: time series "with a trend" are stationary or not? Remove this?

R: A time series is said to be STATIONARY in the wide sense if

- i)  $\mu = \text{constant}$
- ii)  $C = f(\tau), \tau = t_1 - t_2$

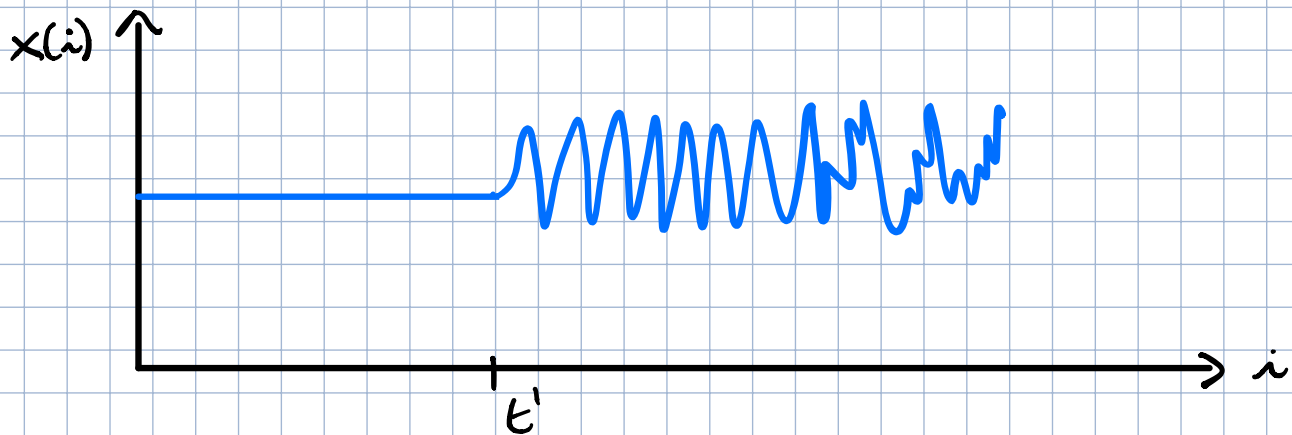


# AUTO-COVARIANCE FOR A GIVEN LENGTH OF TIME



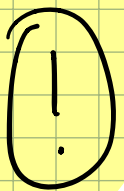
Stationary time series since:

- 1) The mean seems constant
- 2) The similarity does not seem to change with time



This time series is NOT STATIONARY since before  $t'$  the autocovariance for a given  $\tau$  is high, while after  $t'$  is low. Therefore the autocovariance is not just a function of  $\tau$ , but also of time.

The idea is then to study the time series and remove the trend component from it. After that we may estimate the seasonal component and remove it.



OSS : We cannot predict NOISE,  
Because the auto-correlation  
decreases fast with the increase  
of  $\tau$ .

The objective of time series  
analysis is to build a model  
which has a MSE similar to  
the variance of the irregular  
component.

## ASSIGNMENT n° 6

Write a report discussing each of  
the previous assignments